



Machine Learning for Analyzing Human Brain Function

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KDD for the Sciences

- Empirical science has changed forever
 - Online data capture
 - Huge data sets
 - Web-based data collections
 - Machine learning
- Human genome project
 - HMMs for analyzing gene sequences,...
- Sloan sky survey
 - Unsupervised clustering of galaxies, stars,...
- Cell biology
 - Bayesian network models of gene expression

Human Brain Imaging

- fMRI Location with millimeter precision

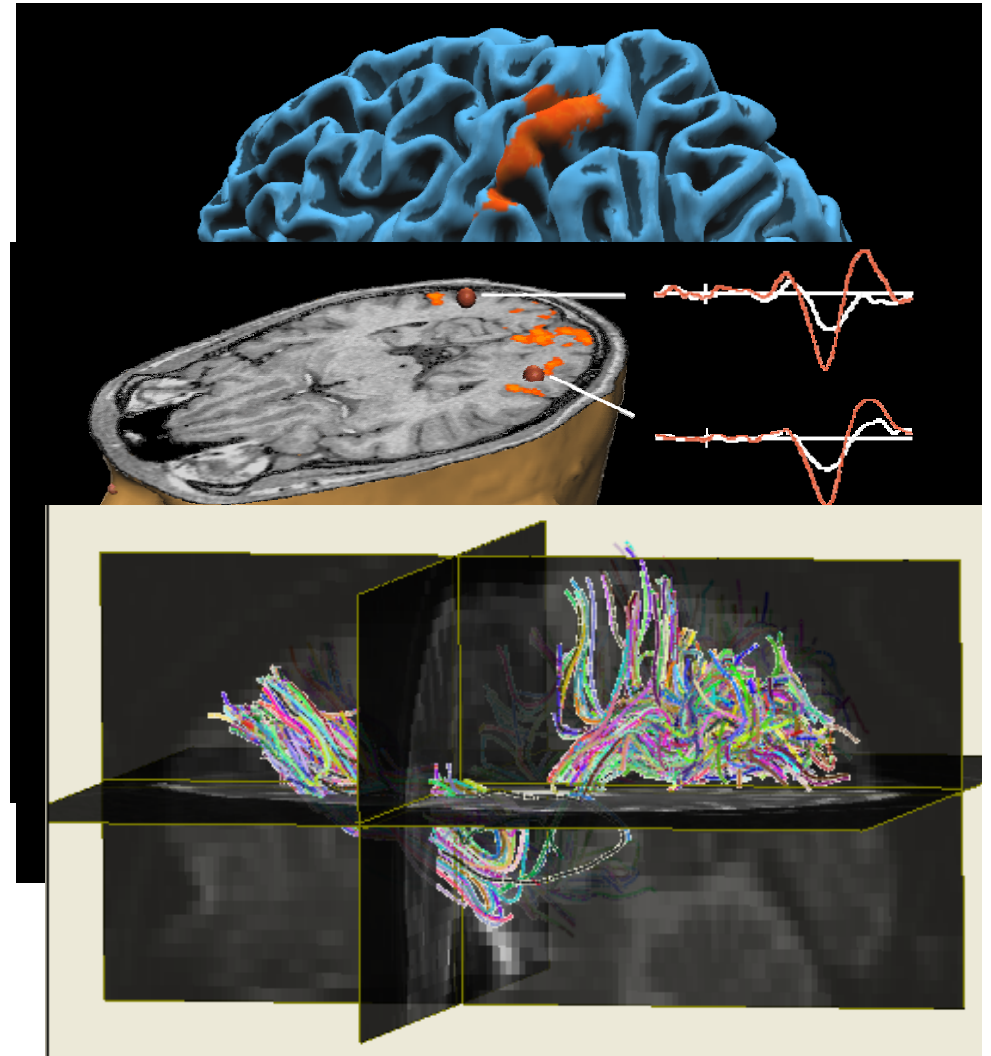
1 mm = 0.0004% of cortex

- ERP Time course with millisecond precision

10 ms = 10 % of human production cycle

- DTI Connections tracing millimeter precision

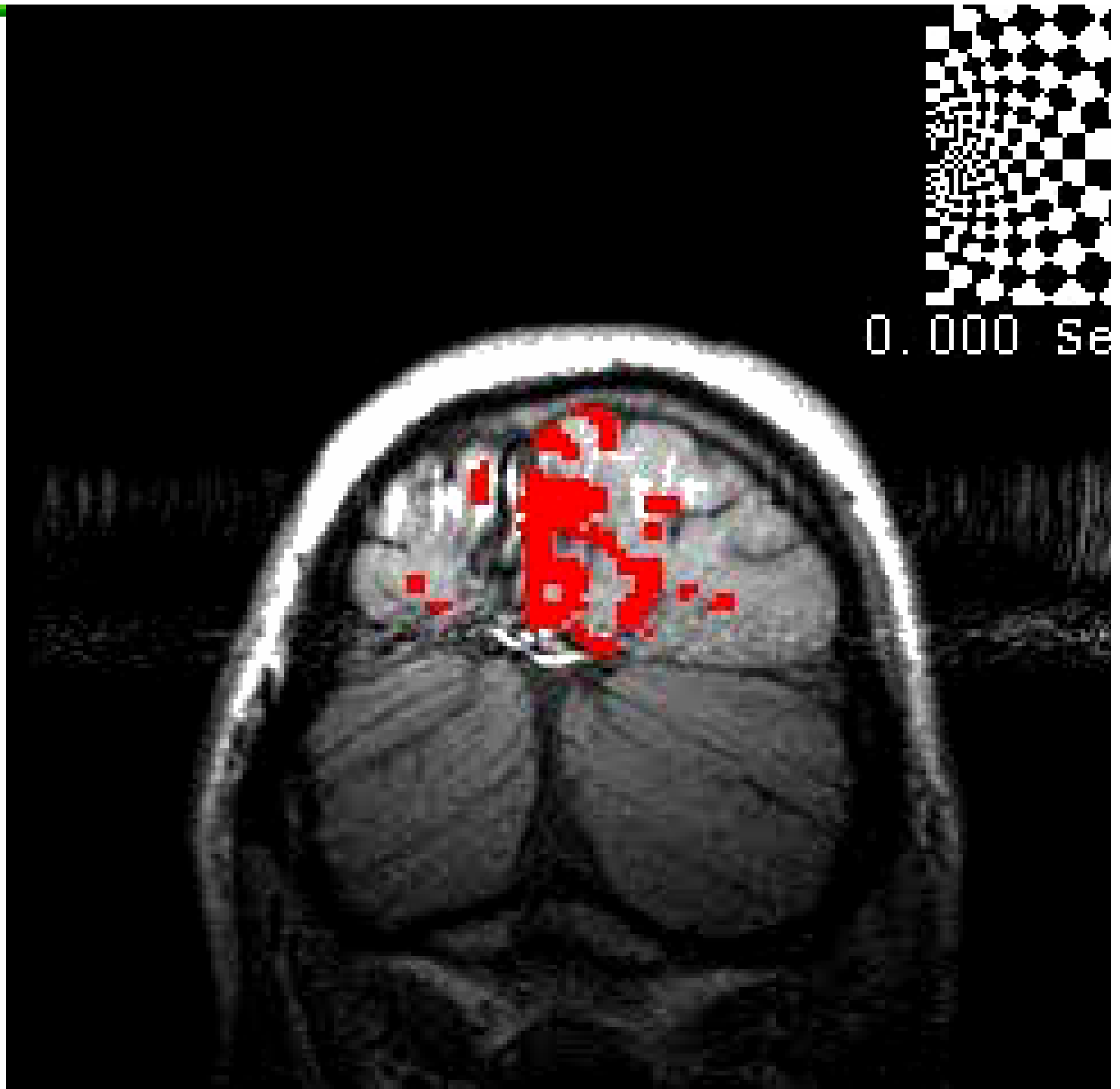
1mm connection ~10k fibers, or 0.0001% of neurons



Functional MRI



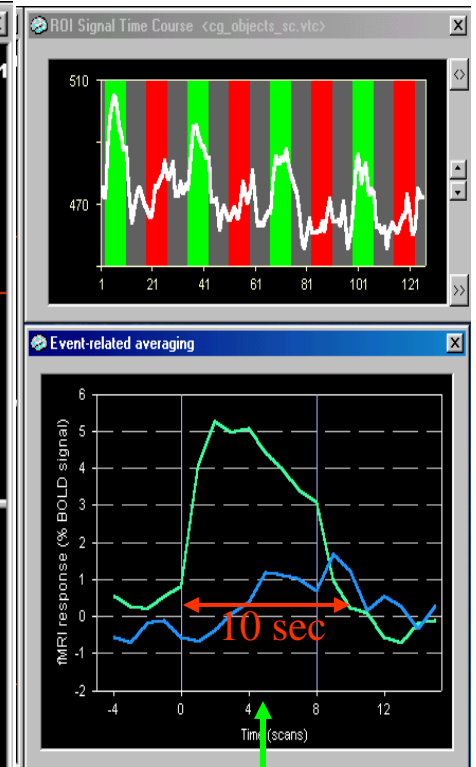
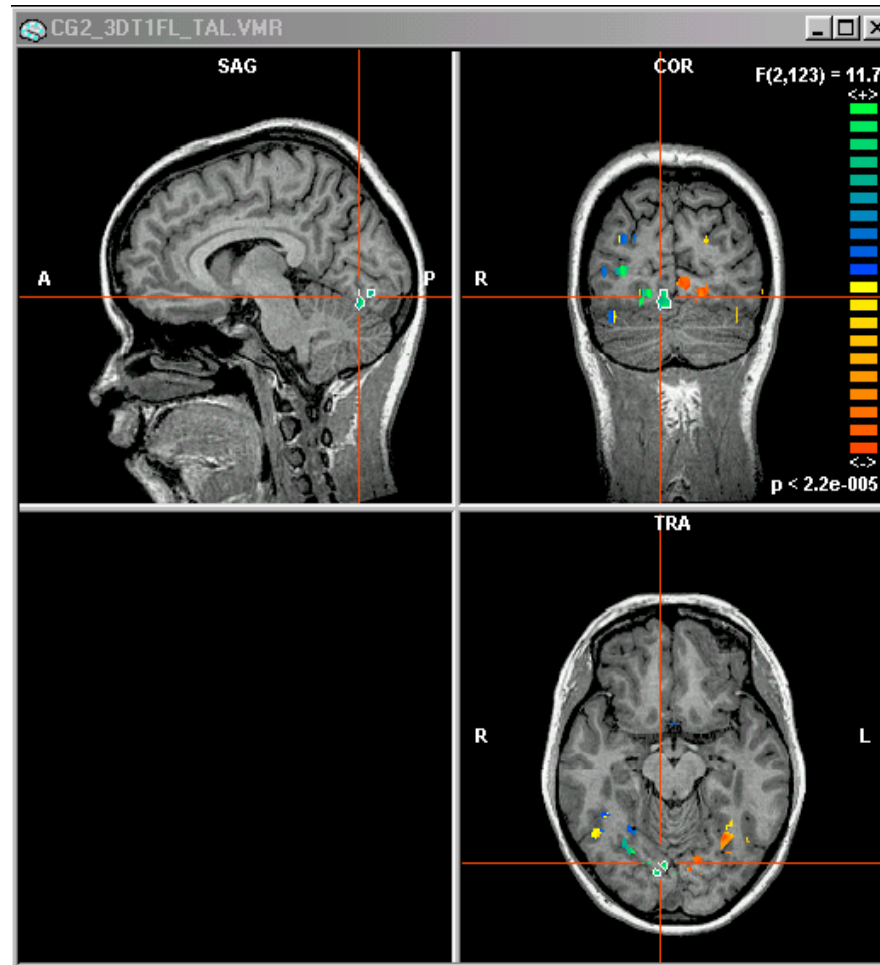
Brain scans can track activation with precision and sensitivity



functional Magnetic Resonance Imaging (fMRI)

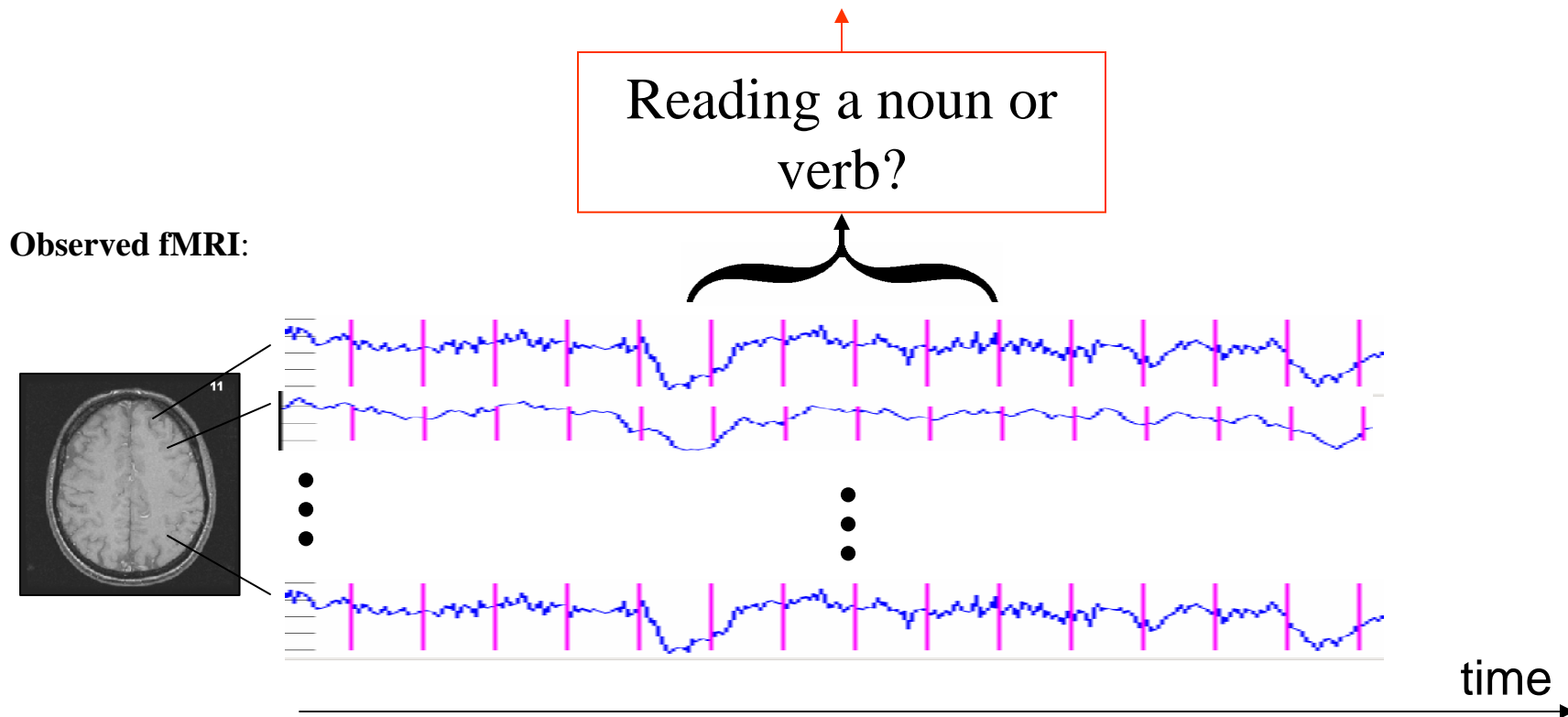
~1 mm resolution
~2 images per sec.
15,000 voxels/image
non-invasive, safe

**measures Blood
Oxygen Level
Dependent (BOLD)
response**



**Typical
impulse
response**

1. Can we distinguish brief cognitive processes using fMRI?



Training Classifiers of Cognitive State

Train classifiers of form:

$fMRI(t, t+\delta) \rightarrow \text{CognitiveStates}$

e.g., $fMRI(t, t+7) = \{\text{ReadNoun}, \text{ReadVerb}\}$

Initially:

- Fixed set of cognitive states
- Fixed time interval $[t, t+\delta]$

Study 1: Word Categories

[with Francisco Pereira, Marcel Just]

For each category (vegetables, tools, trees, fish, dwellings, building parts):

- Presented blocks of 20 words from single* category
- Two blocks of each category
- Blocks from different word categories interleaved

Training Classifier for Word Categories

Learn $fMRI(t, t+20) \rightarrow \text{word-category}(t, t+20)$

- $fMRI(t_1, t_2) = 10^4$ voxels, mean activation of each during interval $[t_1 \ t_2]$

Training methods:

- train single-subject classifiers
- Gaussian Naïve Bayes $\rightarrow P(fMRI \mid \text{word-category})$
- Nearest nbr with spatial-correlation as distance
- SVM

Feature selection: Select n voxels

- Reduce 10^4 voxels to 10^2

Mean Activation per Voxel for Word Categories

Mean
classification
accuracy .90
(tools vs
dwellings,
7 subjects)

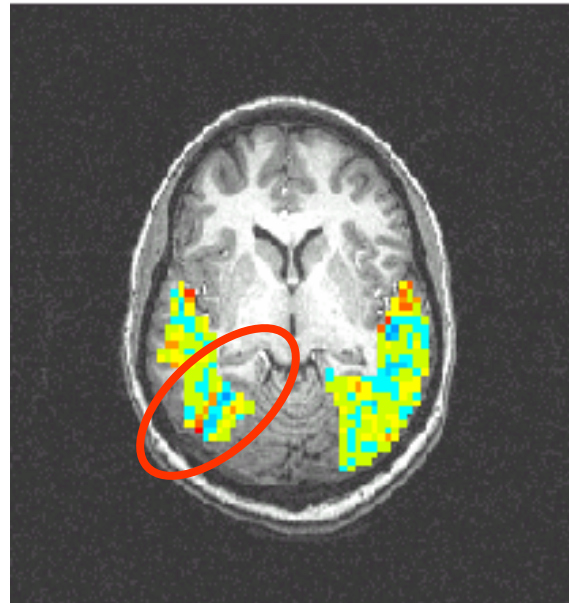
Tools

Dwellings

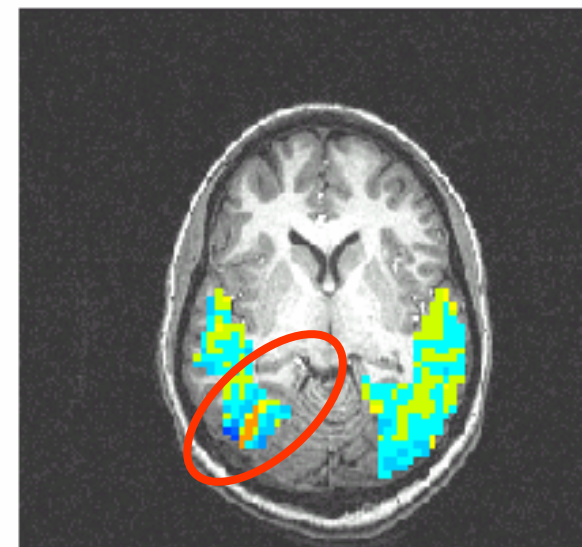
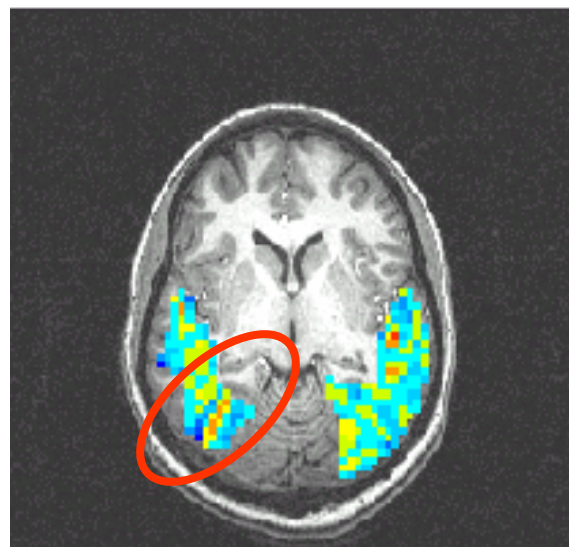
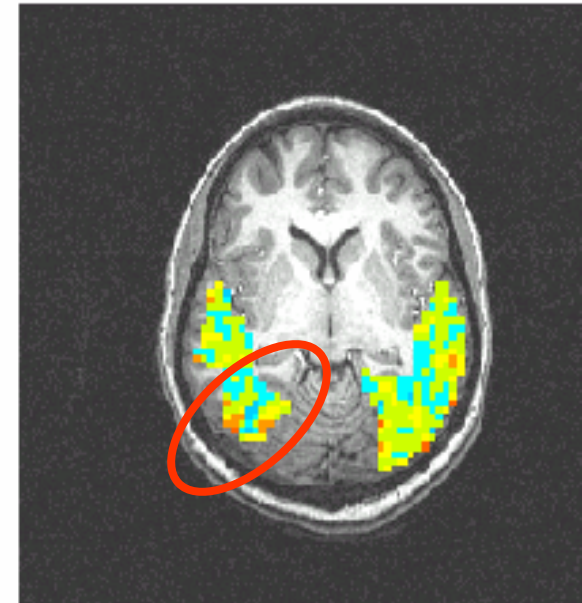
*one horizontal slice,
from one subject,
ventral temporal
cortex*

[Pereira, et al 2004]

Presentation 1



Presentation 2





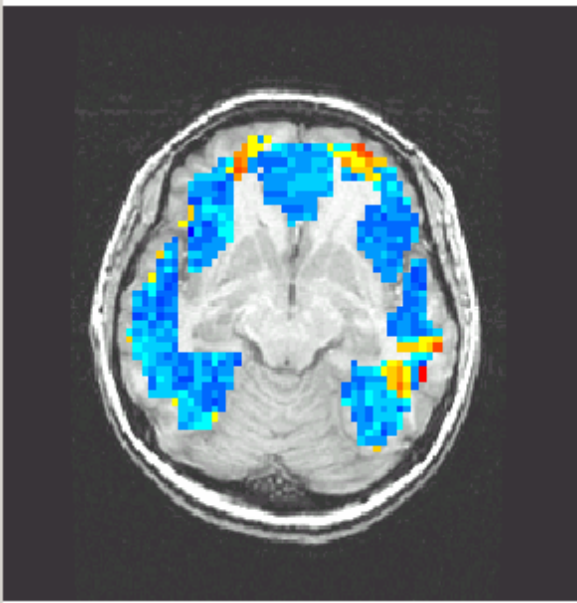
Question:

Where in the brain is the activity that discriminates word category?

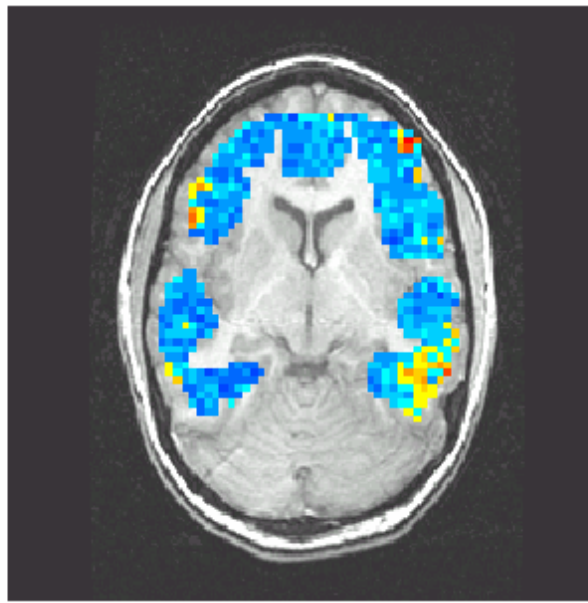
Plot of single-voxel classification accuracies.

Gaussian naïve Bayes classifier

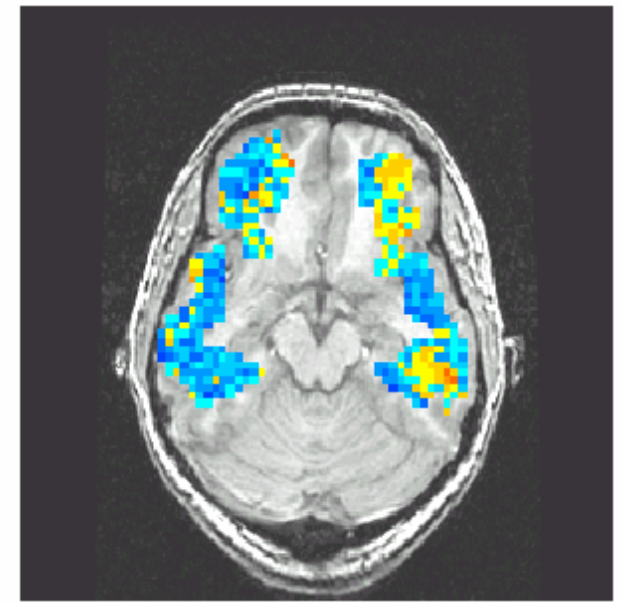
(yellow and red are most predictive).



Subject 1



Subject 2



Subject 3



Question:

Do different people's brains
'encode' semantic categories
using the same spatial patterns?

No.

But, there are cross-subject
regularities in "distances"
between categories, as
measured by classifier
error rates.

Six-Category Study: Pairwise Classification Errors (ventral temporal cortex)

* Worst * Best

| | Fish | Vegetables | Tools | Dwellings | Trees | Bldg Parts |
|-------------|------------|------------|------------|------------|------------|------------|
| Subj1 | .20 | .55 * | .20 | .15 | .15 | .05 * |
| Sub2 | .10 * | .55 * | .35 | .20 | .10 * | .30 |
| Sub3 | .20 | .35 * | .15 * | .20 | .20 | .20 |
| Sub4 | .15 | .45 * | .15 | .15 | .25 | .05 * |
| Sub5 | .60 * | .55 | .25 | .20 | .15 * | .15 * |
| Sub6 | .20 | .25 | .00 * | .30 * | .30 * | .05 |
| Sub7 | .15 | .55 * | .15 | .25 | .15 | .05 * |
| Mean | .23 | .46 | .18 | .21 | .19 | .12 |

Lessons Learned

Yes, one can train machine learning classifiers to distinguish a variety of mental states

- Nouns about “tools” vs. nouns about “building parts”
- Noun vs. Verb
- Ambiguous sentence vs. unambiguous
- Picture vs. Sentence

Failures too:

- True vs. false sentences
- Negative vs. affirmative sentences

ML methods:

- NNbr, Naïve Bayes, SVMs, NNets, ...
- Case study in high dimensional, noisy classif [MLJ 2004]
- New approaches to feature selection

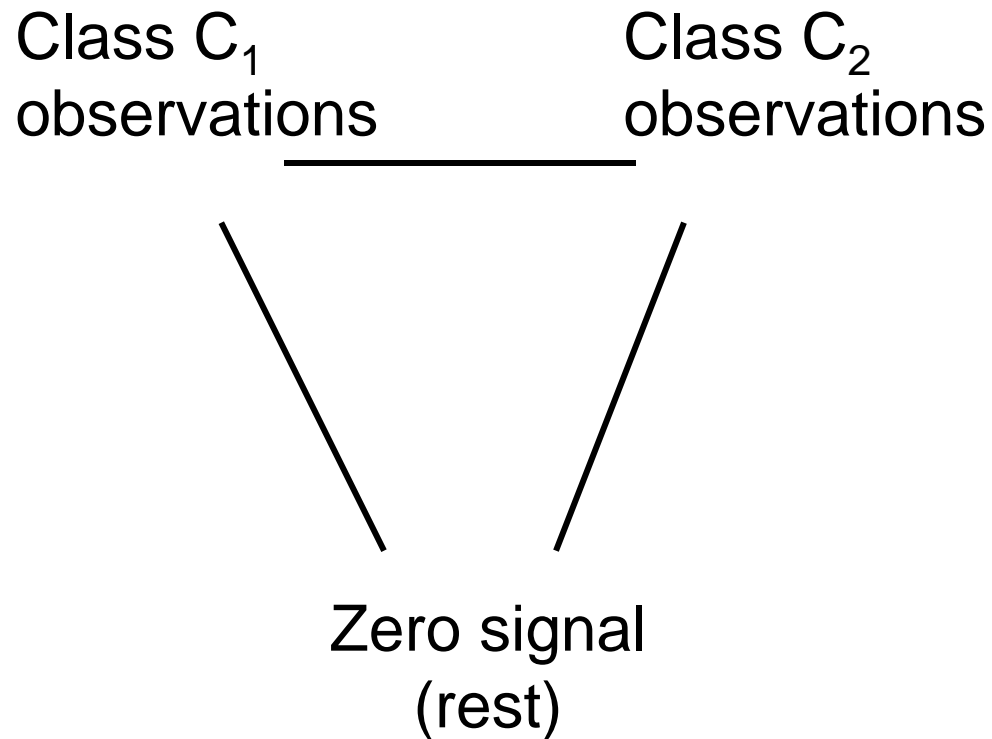
Which Feature Selection Strategy to Use?

Wish to learn $F: \langle x_1, x_2, \dots, x_n \rangle \rightarrow \{A, B\}$

- Feature selection often reduces error 30-40%
- Conventional wisdom: pick features x_i that best distinguish between classes A and B
 - E.g., sort x_i by mutual information with target class
- Surprise:
Alternative strategy works better (23/28 subjects)
 - We have three types of data: subject is performing task A, task B, or resting
 - Pick features that distinguish whether or not subject is resting

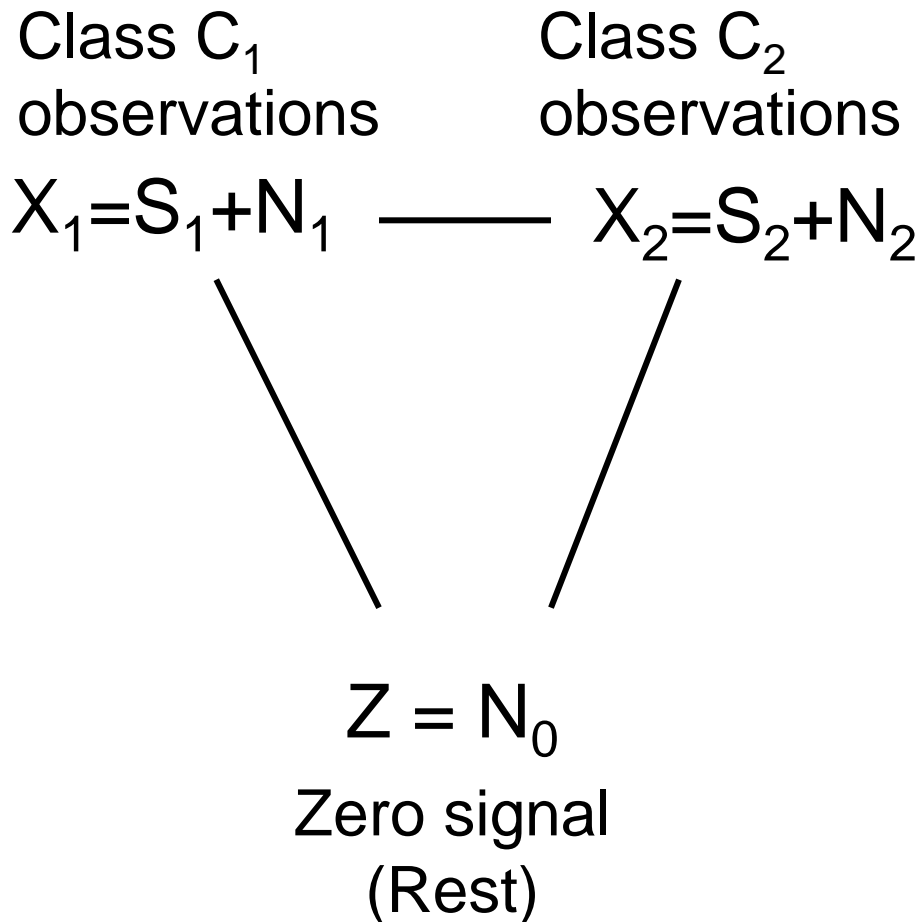
“Zero Signal” learning setting.

Select features based on $\text{discrim}(C_1, C_2)$ or $\text{discrim}(Z, C_i)$?



“Zero Signal” learning setting.

Select features based on $\text{discrim}(C_1, C_2)$ or $\text{discrim}(Z, C_i)$?



Goal: learn $f: X \rightarrow Y$ or $P(Y|X)$

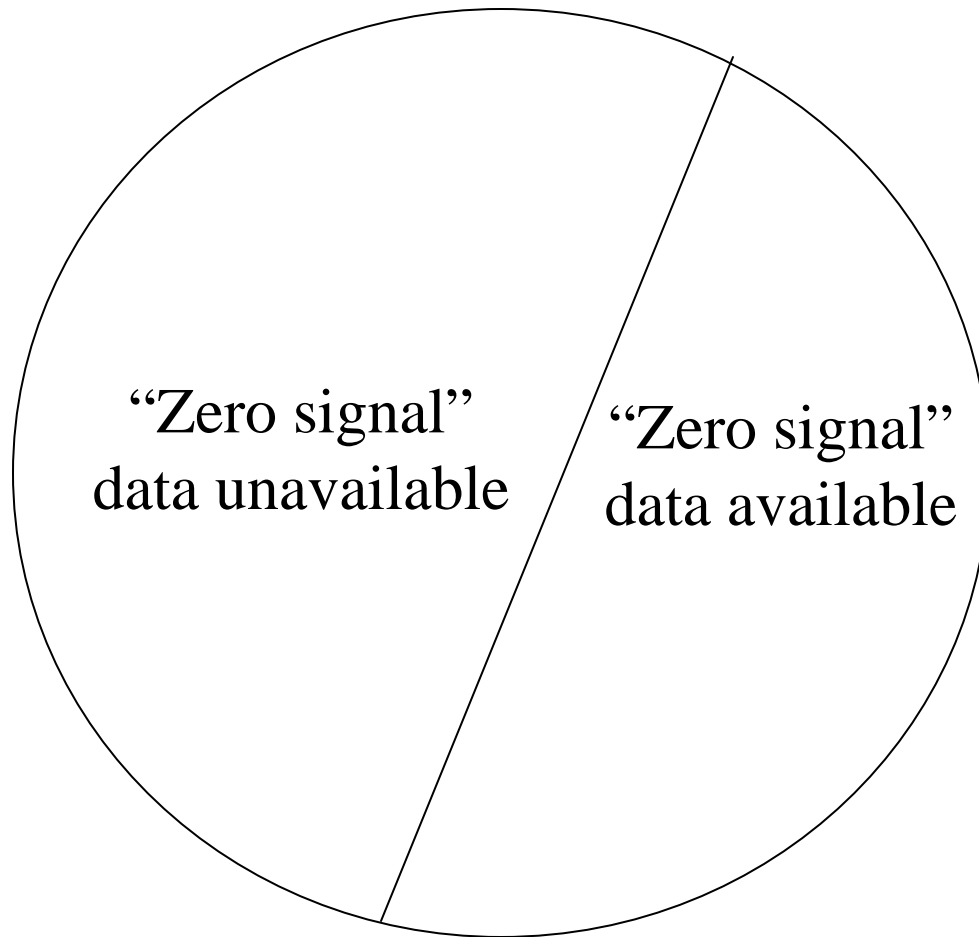
Given:

1. Training examples $\langle X_i, Y_i \rangle$ where $X_i = S_i + N_i$, signal $S_i \sim P(S|Y = Y_i)$, noise $N_i \sim P_{\text{noise}}$
2. Observed noise with zero signal $N_0 \sim P_{\text{noise}}$

Discrim(C_1, C_2) or Discrim(C_i, Rest)?

[Jay Pujara, 2005]

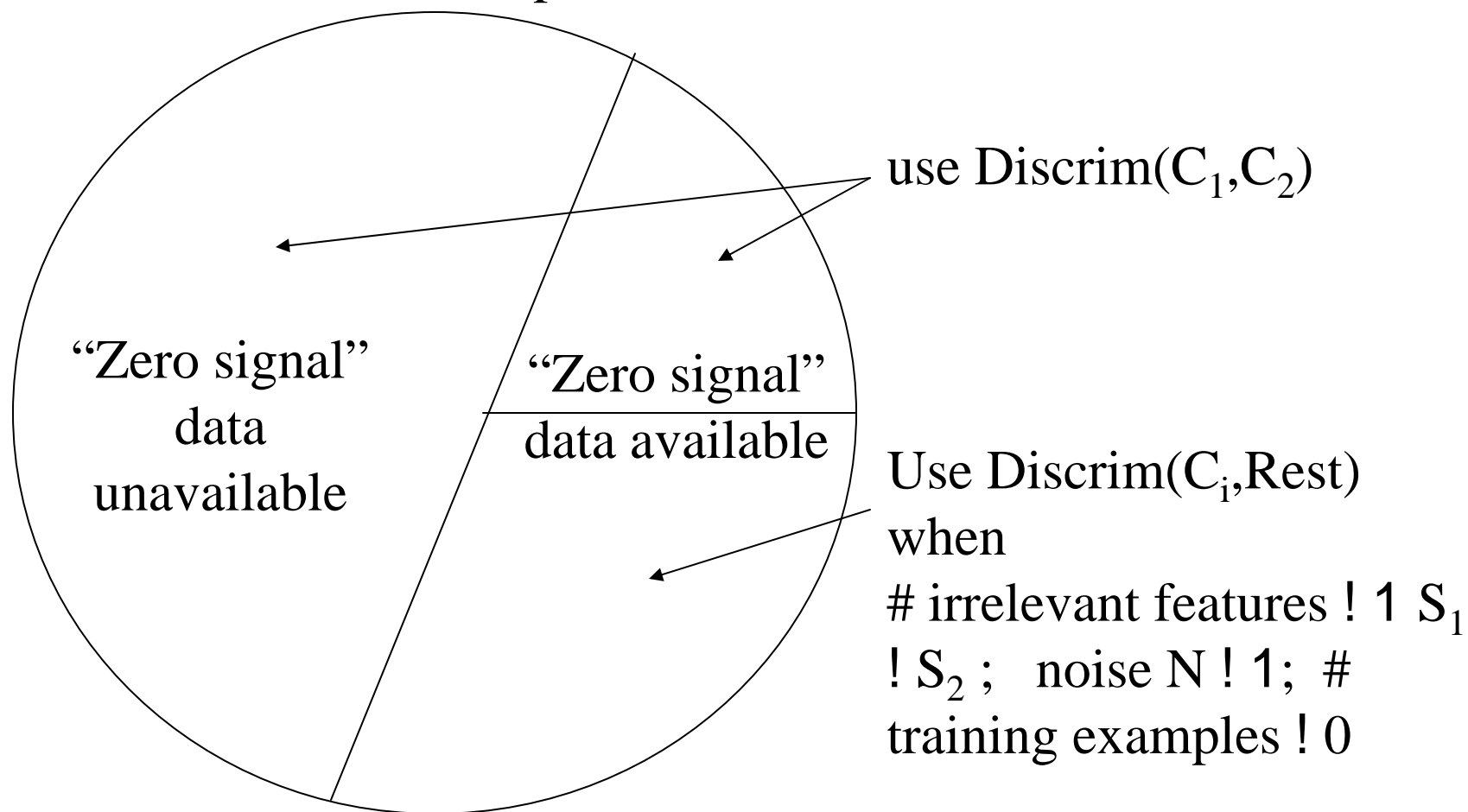
Feature selection problems



Discrim(C_1, C_2) or Discrim(C_i, Rest)?

[Jay Pujara, 2005]

Feature selection problems



2. Can we classify/track *multiple overlapping processes*?

Cognitive processes:

Read sentence

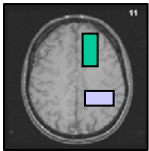
View picture

Decide whether consistent

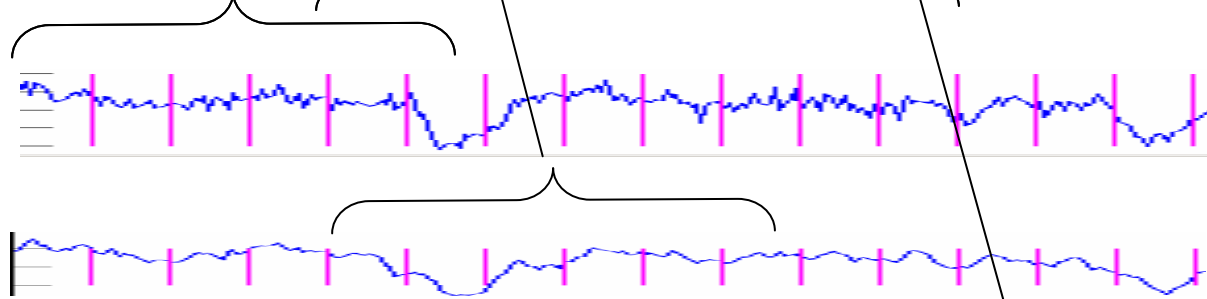
?

Observed fMRI:

cortical region 1:



cortical region 2:



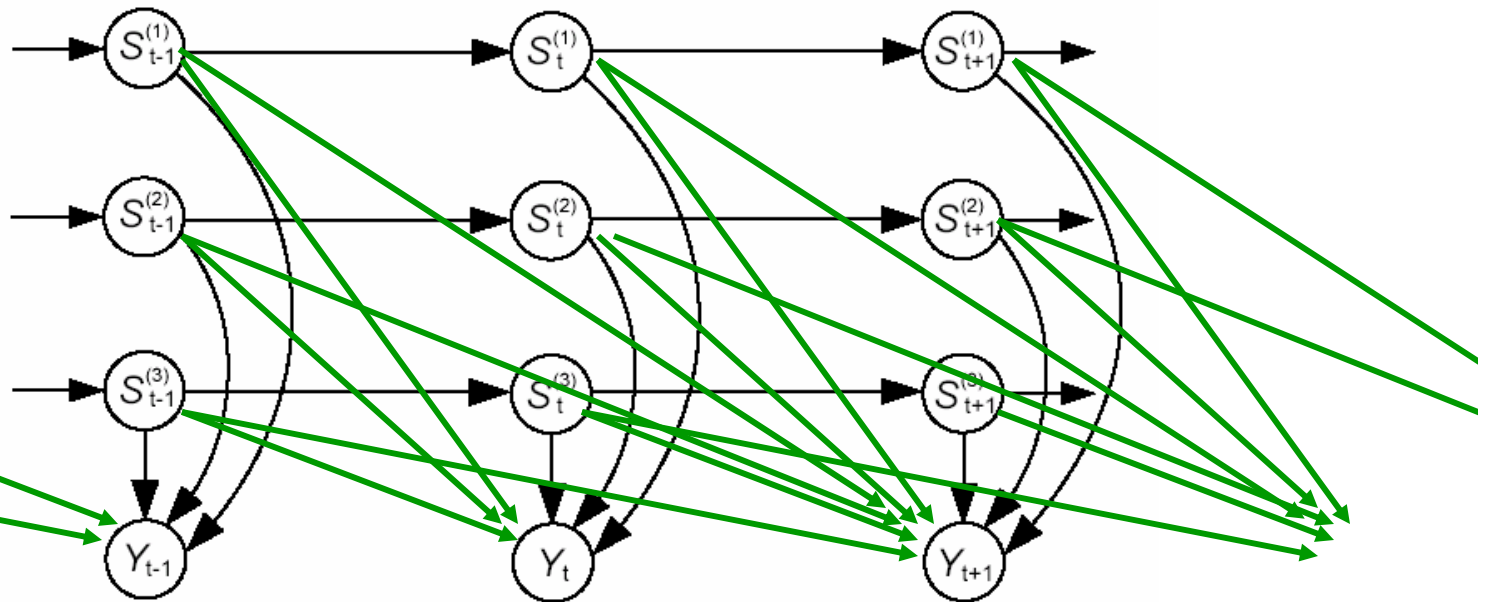
Observed button press:



Bayes Net related State-Space Models

HMM's, DBNs, etc. e.g., [Ghahramani, 2001]

Cognitive
subprocesses
/ state
variables:

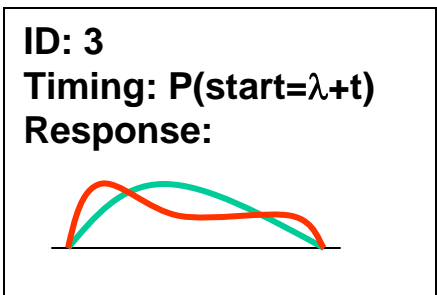
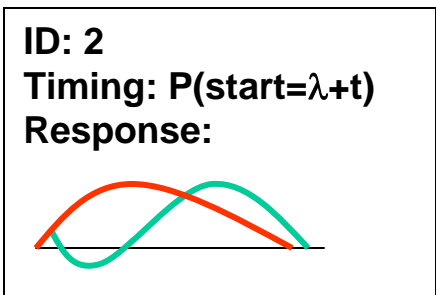
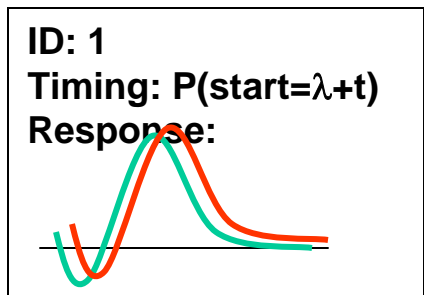


fMRI:

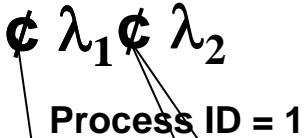
see [Hojen-Sorensen et al, NIPS99]

Hidden Process Models

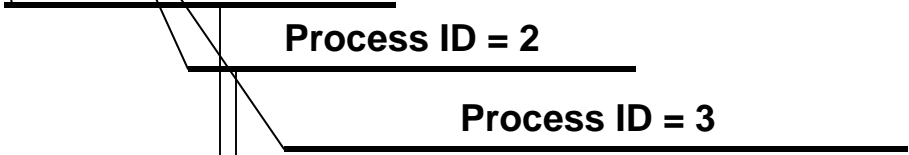
Processes:



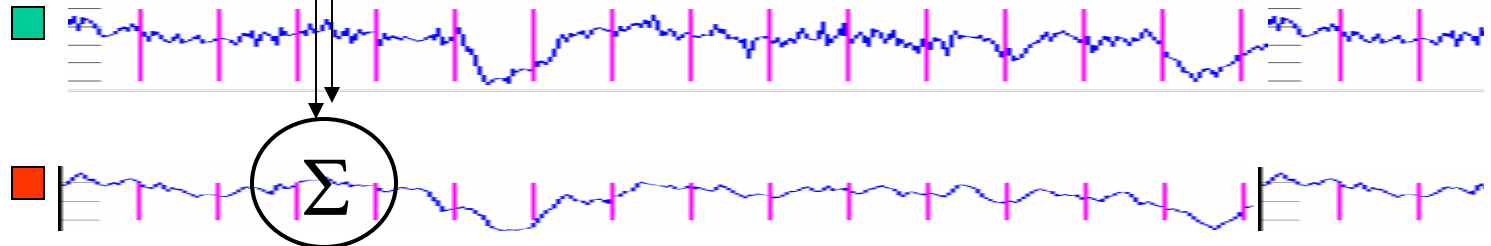
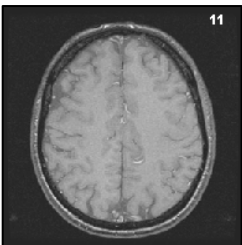
Time landmarks:



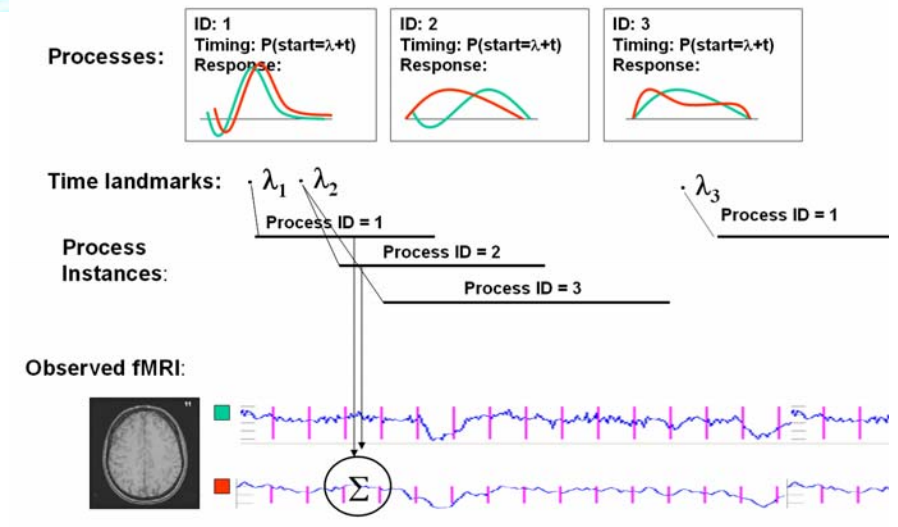
Process Instances:



Observed fMRI:



Hidden Process Models



- Probability of fMRI observation $y_{v,t}$

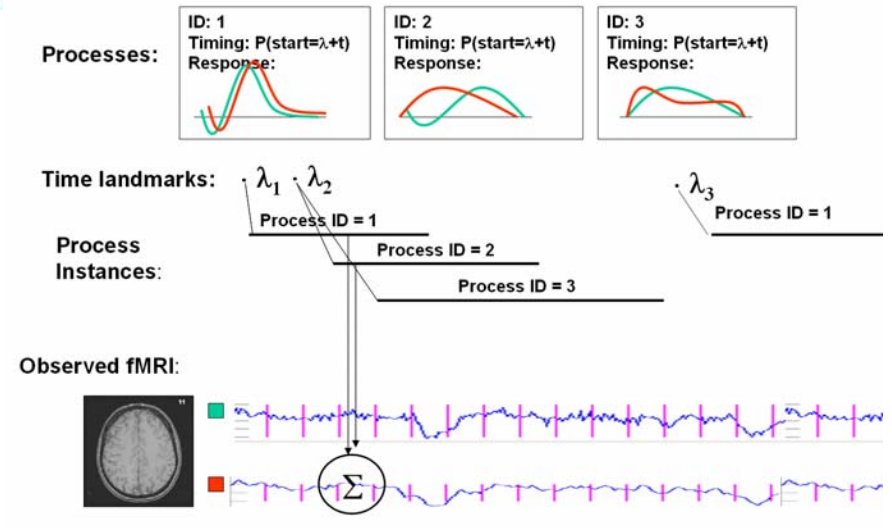
$$P(y_{v,t} | HPM, INT) = N(\mu_{v,t}, \sigma_v)$$

where

$$\mu_{v,t} = \sum_{i \in \text{active process instances}} W_i(v, t - \text{start}(i))$$

learned

Hidden Process Models

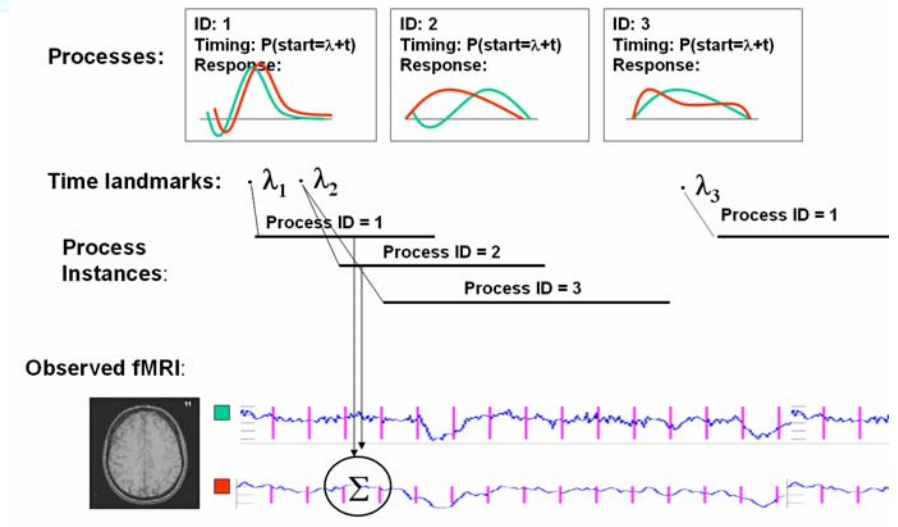


- Probability of process instance k beginning at time t

$$P(\text{start}_k = t) = \theta_{t-\lambda}$$

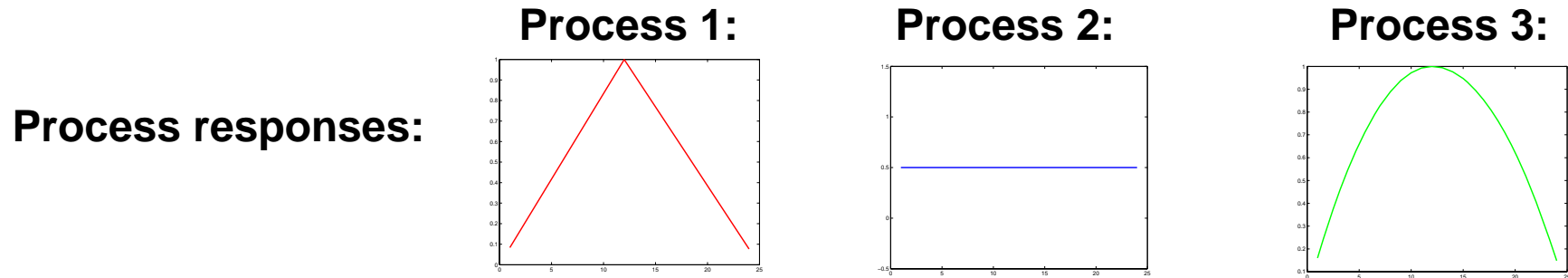
↑
learned

Learning HPMs



- When process IDs, start times *known*:
 - Least squares regression, eg. Dale[HBM,1999]
 - Ordinary least sq if assume noise indep over time
 - Generalized least sq if assume autocorrelated noise
- When start times *unknown*:
 - EM algorithm
 - Repeat:
 - E: estimate probability distribution over start times
 - M: choose parameters to maximize expected data likelihood

Synthetic Noise-Free Data Example

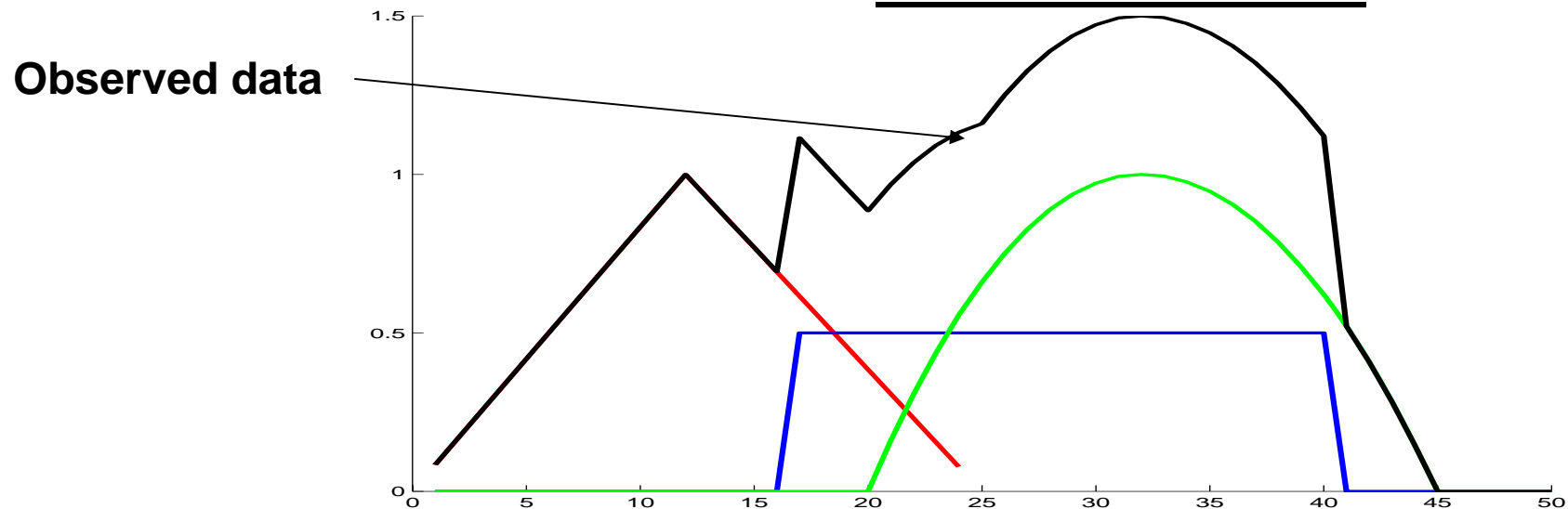


ProcessID=1, S=1

Process instances:

ProcessID=2, S=17

ProcessID=3, S=21



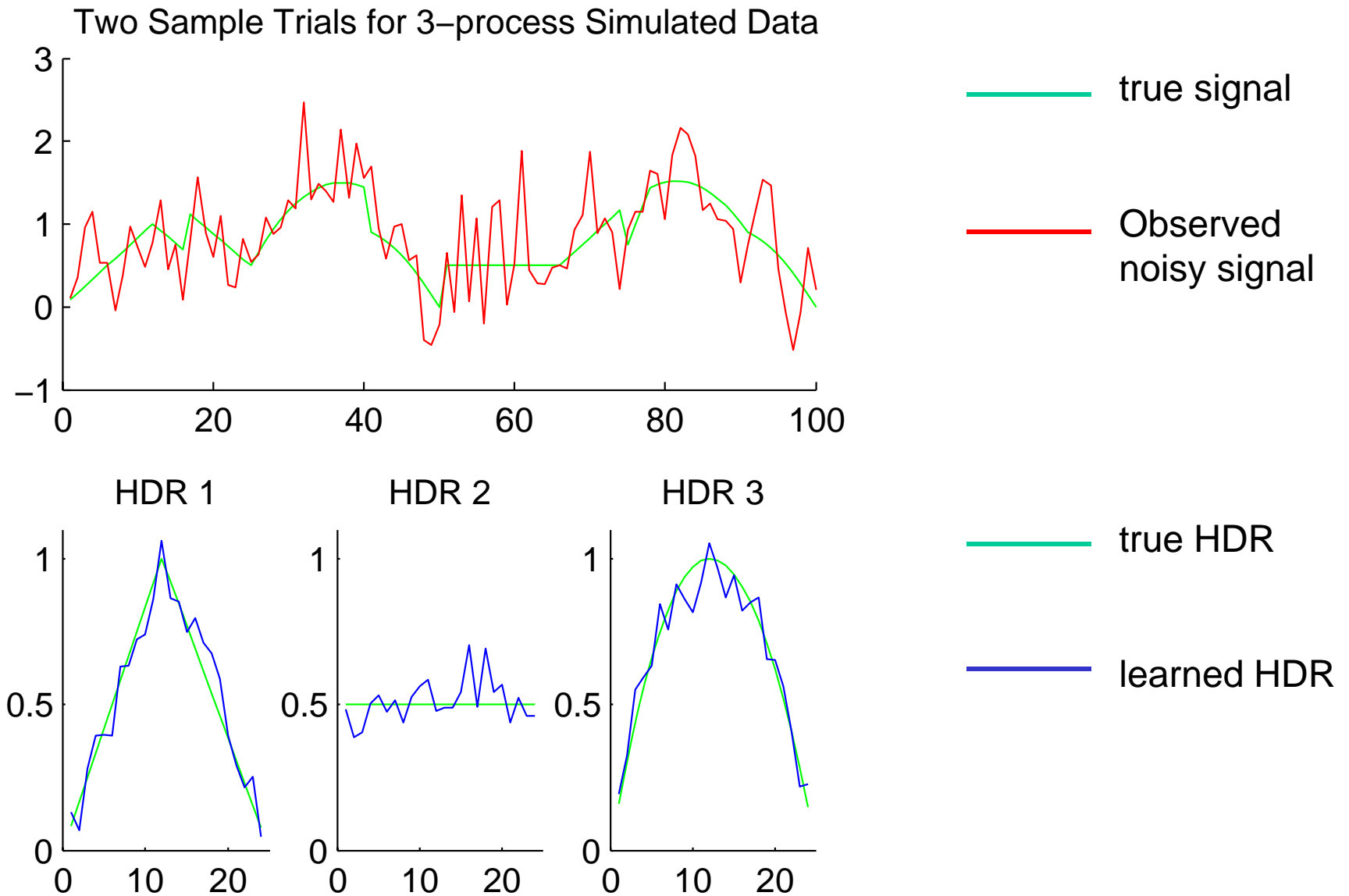
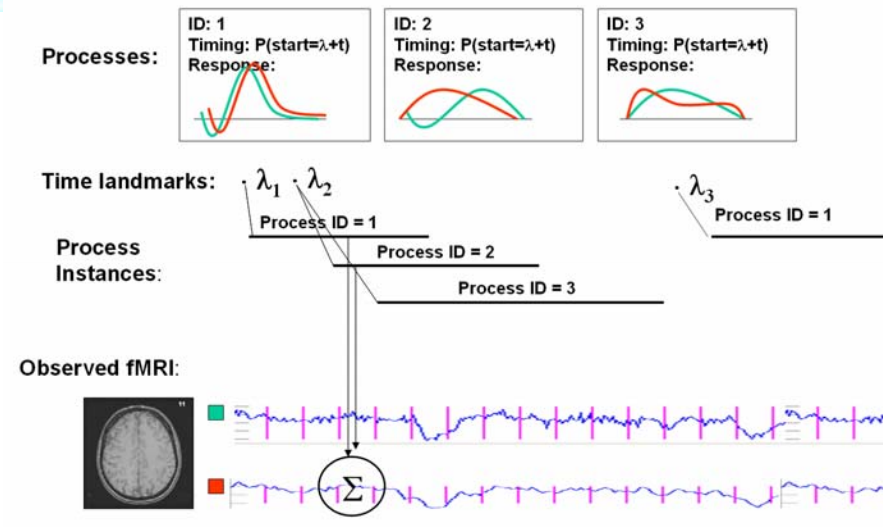


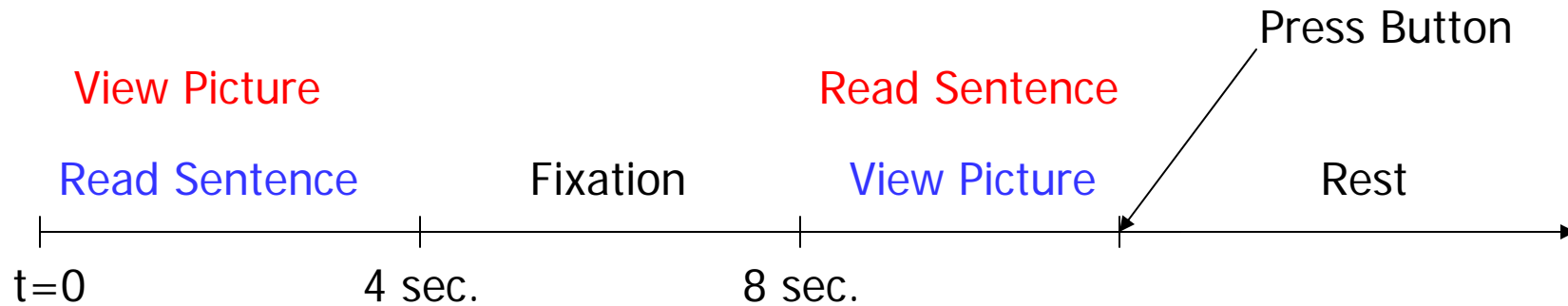
Figure 1. The learner was given 80 training examples with known start times for only the first two processes. It chooses the correct start time (26) for the third process, in addition to learning the HDRs for all three processes.

Using HPMs



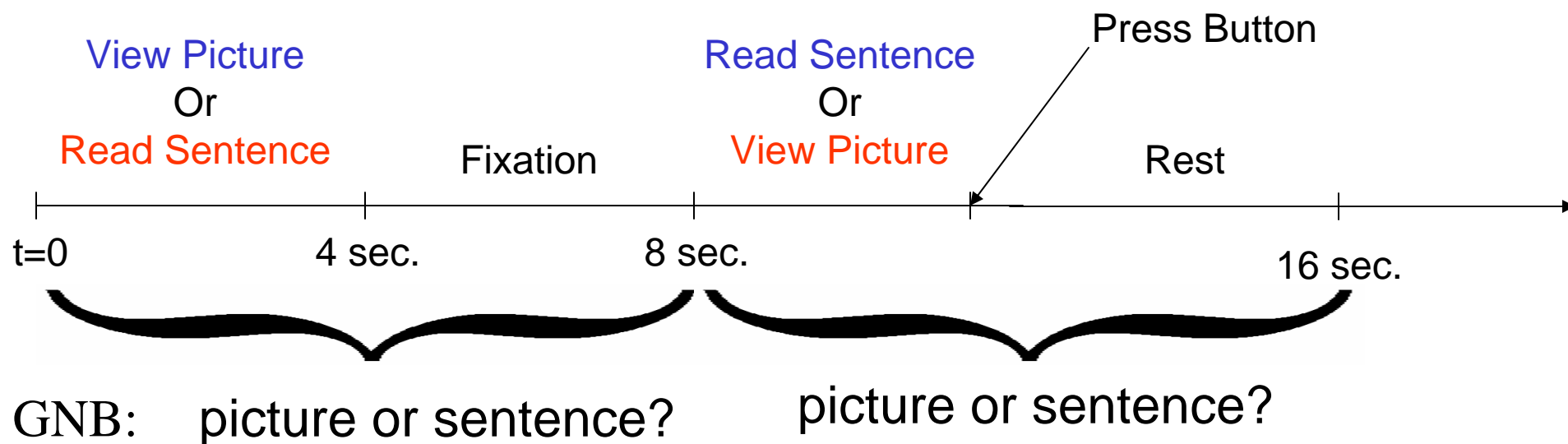
- Given an HPM and data set
 - Assign the ProcessIDs and StartTimes that maximize $P(\text{ObservedData} \mid \text{ProcessIDs}, \text{StartTimes})$
 - Subject to any known processIDs, and prior probabilities on their StartTimes
- Classification = assigning processIDs

Study: Pictures and Sentences



- 13 normal subjects.
- 40 trials per subject.
- Sentences and pictures describe 3 symbols: *, +, and \$, using 'above', 'below', 'not above', 'not below'.
- Images are acquired every 0.5 seconds.

Standard classifier formulation

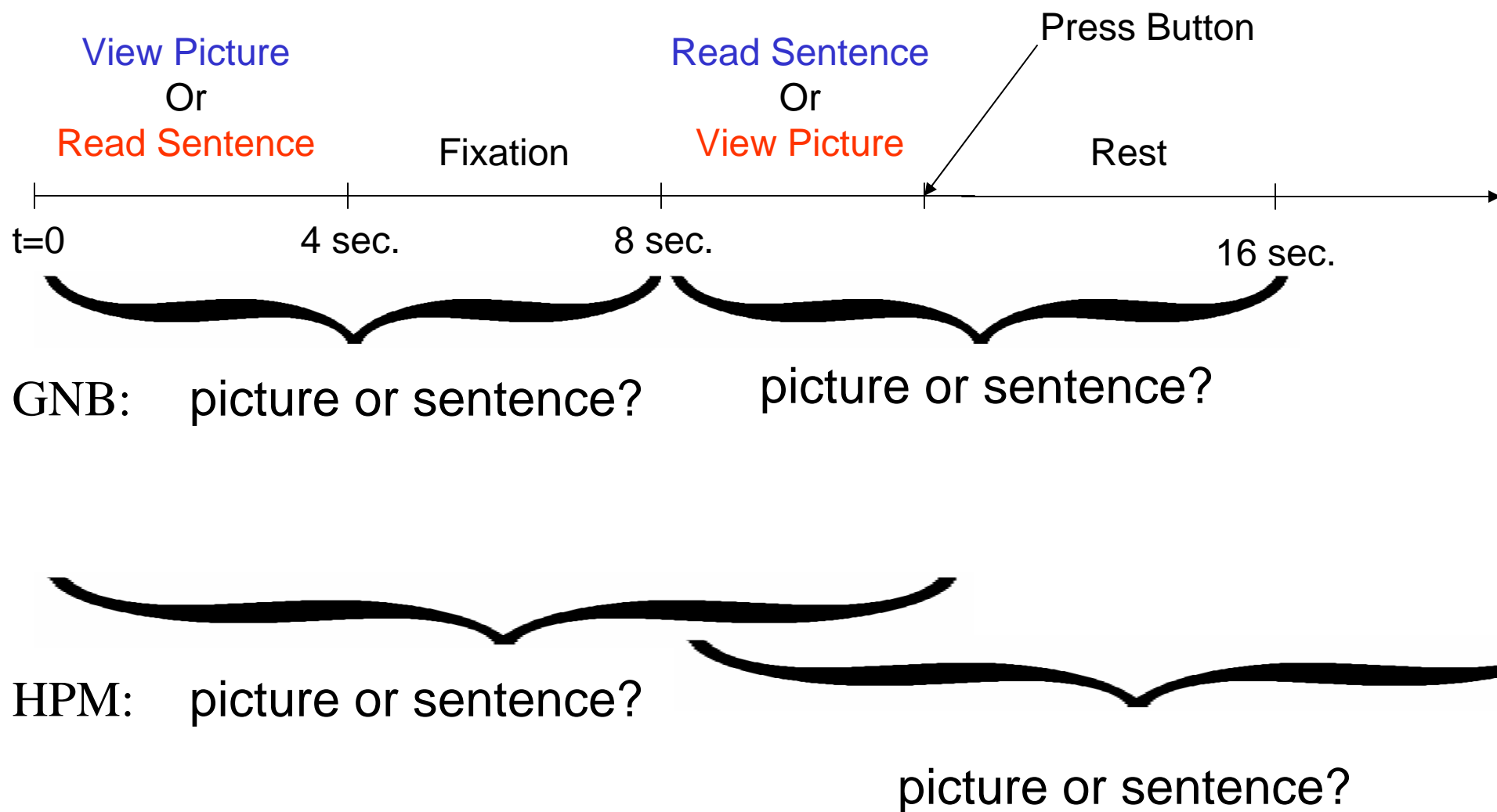


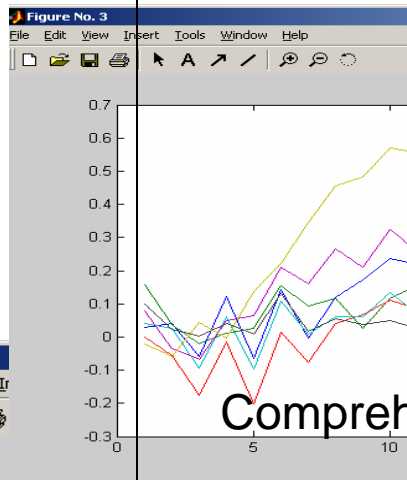
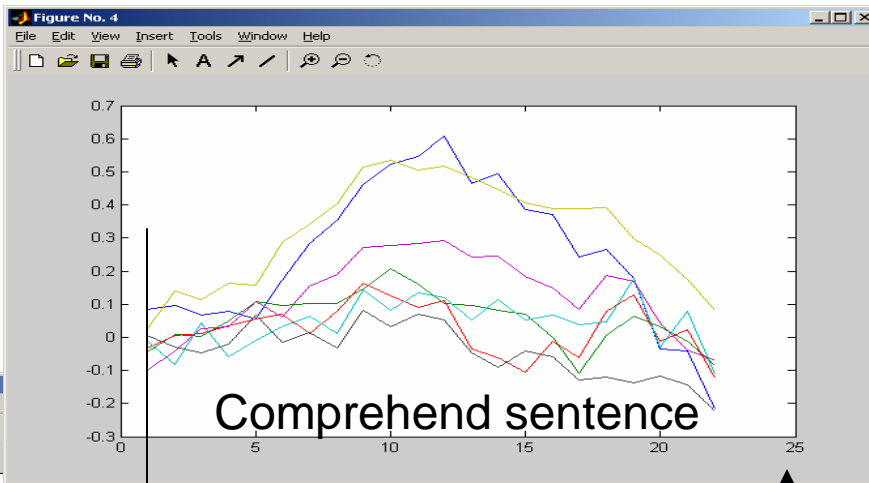
Standard formulation of classification problem.

Train on labeled data, assuming known IDs, StartTimes

Fails to account for overlapping influences of processes

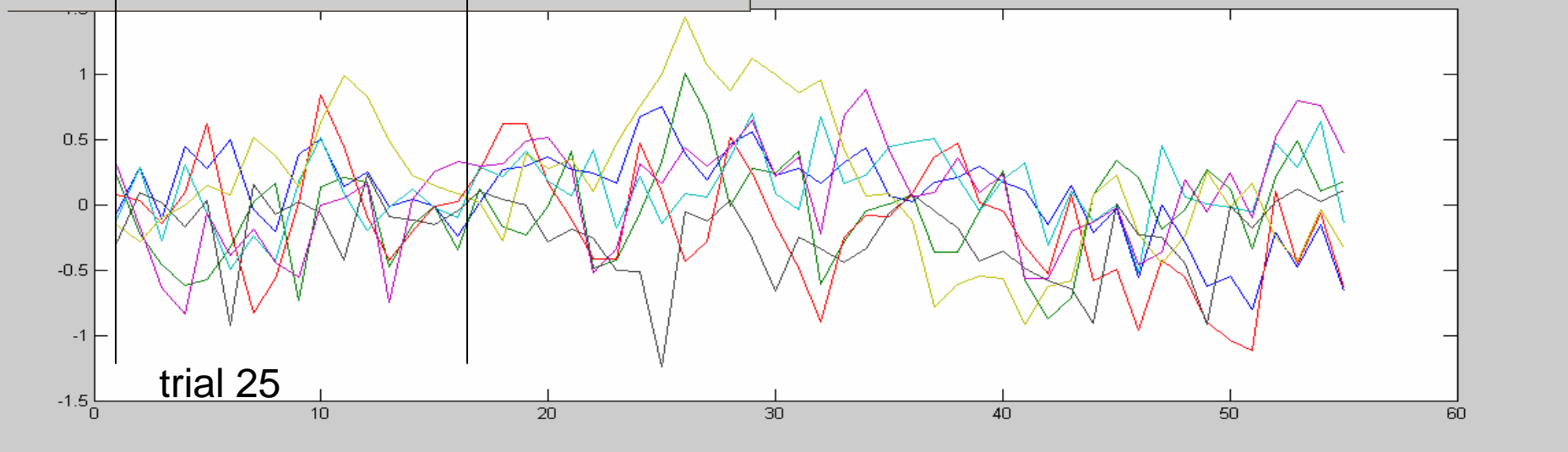
HPM classifier accounts for overlap





0.1
View Ir

Models learned from labeled data

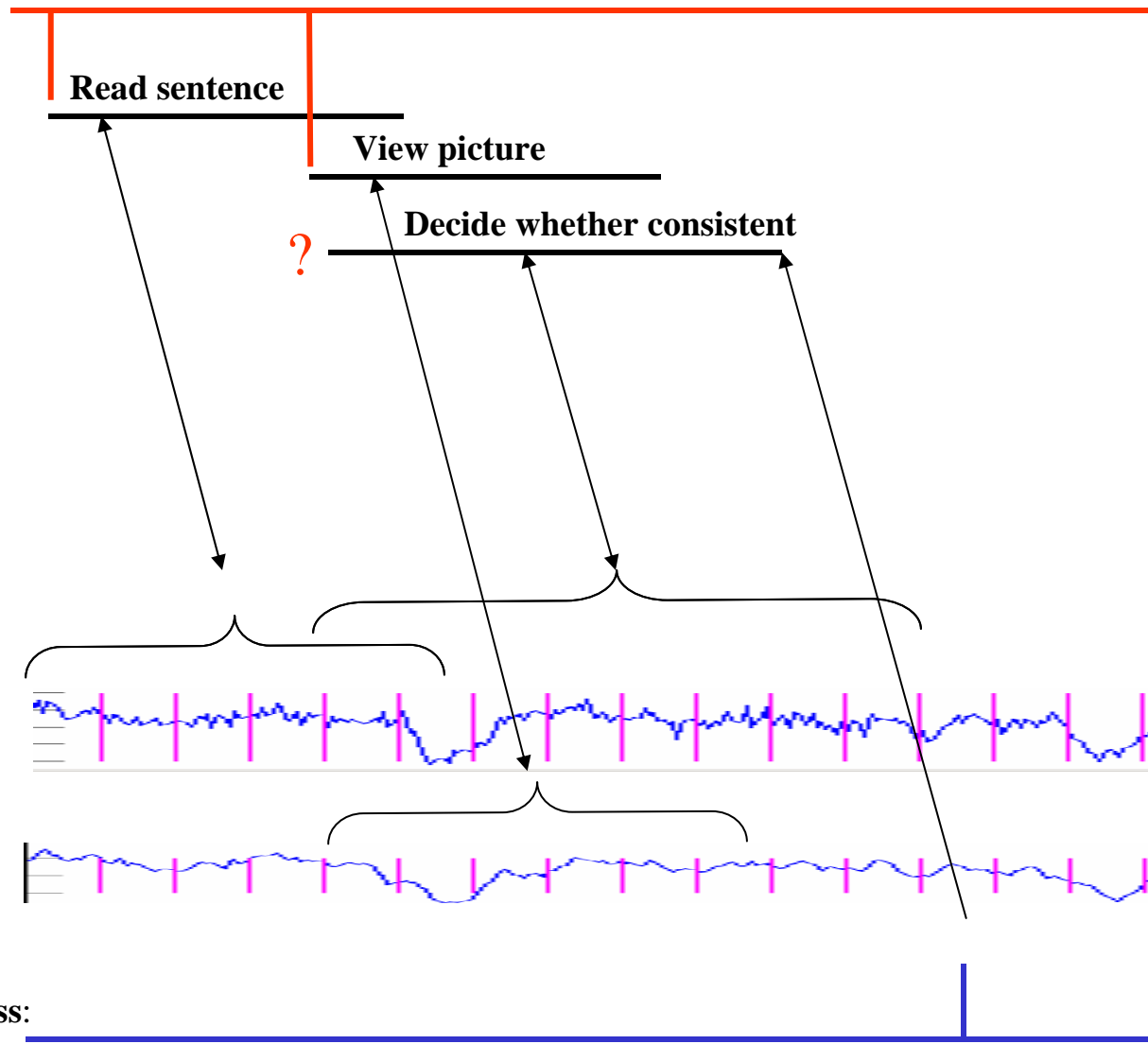


GNB vs. HPM Classification

- GNB: assumes non-overlapping processes
- HPM: simultaneous classification of multiple overlapping processes
- Average improvement of 15% in classification error using HPM vs GNB
- E.g., subject 04847
 - GNB classification error: 0.14
 - HPM classification error: 0.09

Learning hidden processes with *unknown* start times

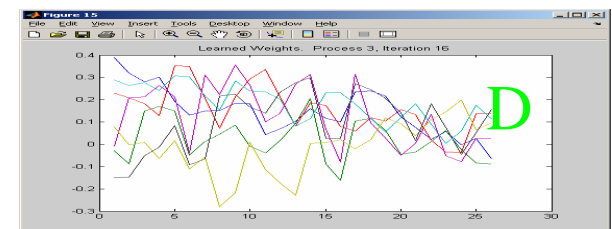
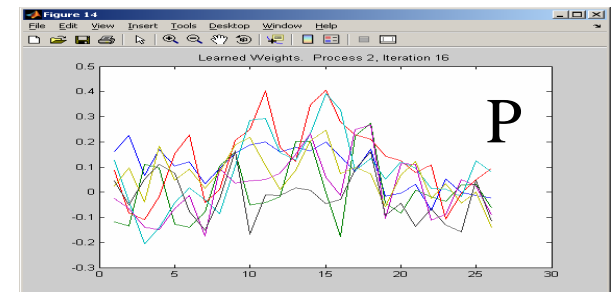
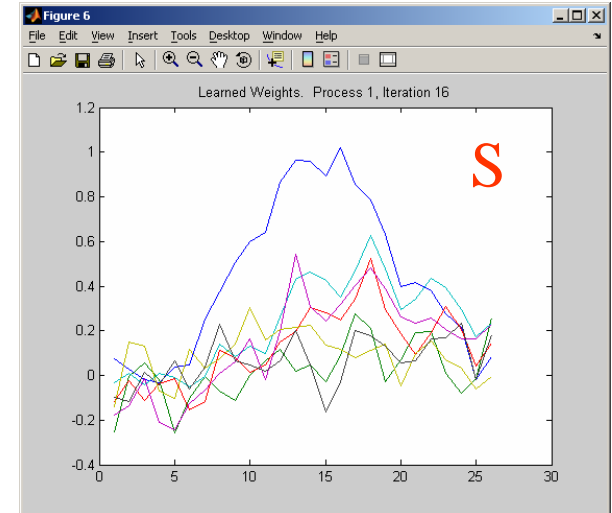
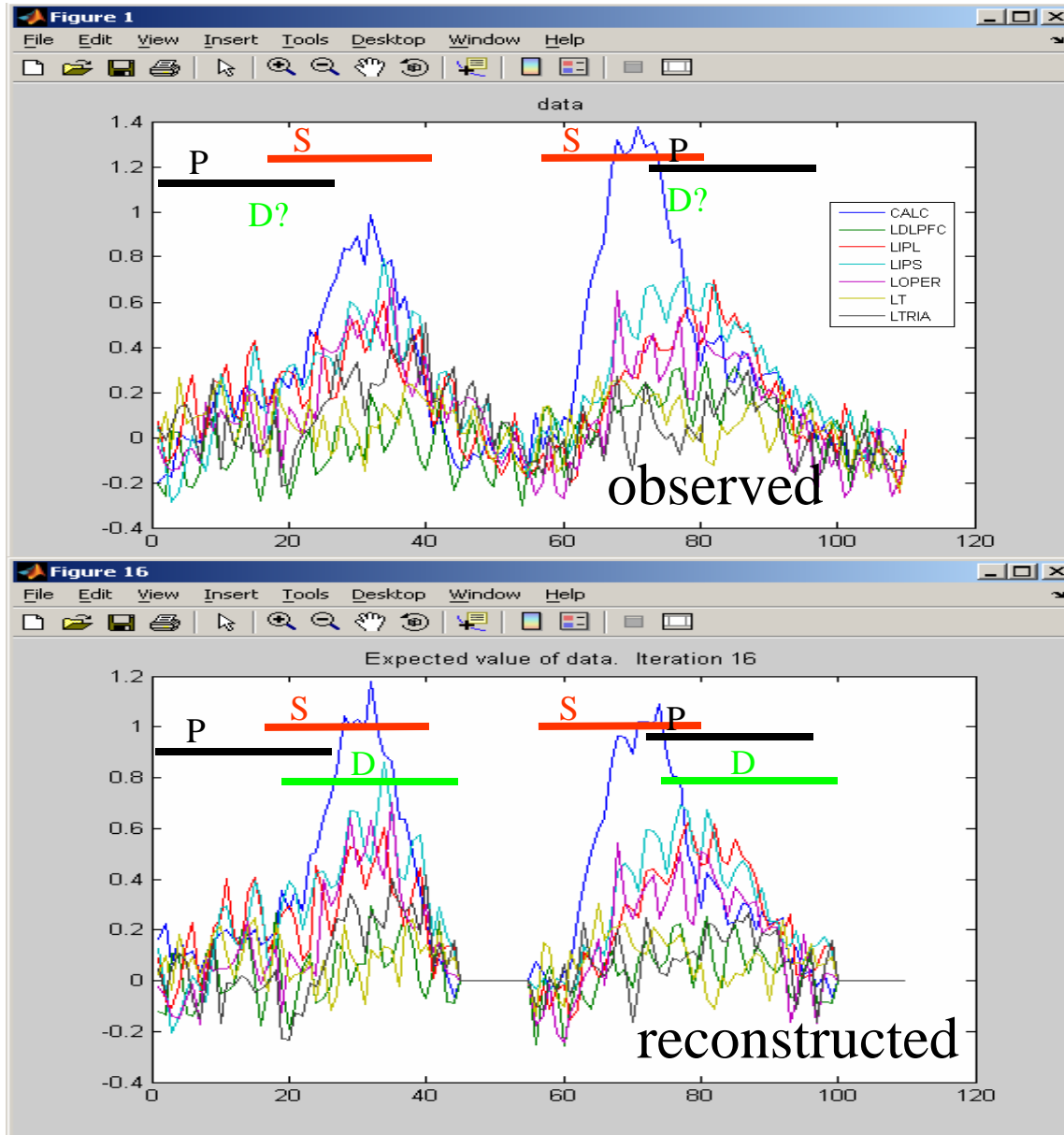
Input stimuli:



Observed button press:

Learned HPM with 3 processes (S,P,D), and R=13sec (TR=500msec).

Learned models



D start time chosen by program as $t+18$

HPM's on Picture-Sentence task

- HPM classification accuracy for Picture/Sentence better than Gaussian Naïve Bayes (GNB)
- HPMs are a strict generalization of GNB
- Model with 2 or 3 cognitive processes?
 - How would we know ground truth?
 - Cross validated data likelihood $P(\text{testData} \mid \text{HPM})$
 - Better with 3 processes than 2
 - Cross validated classification accuracy
 - Better with 3 processes than 2

Summary

- Classification of cognitive processes from fMRI brain image data
 - Works!
 - Feature selection with “zero signal” data
- Learning models of overlapping, hidden cognitive processes
 - Hidden Process Model formalism
 - Superiority over standard classification
 - Base for studying hidden human processes